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ON S-METRIC SPACES WITH SOME TOPOLOGICAL ASPECTS

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ABSTRACT. The notion of a metric space is an important tool in functional analysis, nonlinear analysis and especially in topology. New generalizations of metric spaces have been introduced in recent years. For instance, S-metric and b-metric spaces are among the recent generalizations of a metric space. Fixed point theory has been intensively studied and generalized using various approaches on these new spaces. In this paper we consider the relationships among a metric, an S-metric and a b-metric. In this context, we define the topological equivalence between a metric and an S-metric. Especially, we focus on the fact that every S-metric does not always generate a metric. This is the main motivation of the recent fixed point studies for self-mappings on an Smetric space. Also we revisit the notion of a metric generated by an S-metric. We support our theoretical findings by necessary illustrative examples. As a consequence, existing studies based on the metric generate a metric or not.

1. INTRODUCTION AND PRELIMINARIES

Let (X, d) be a metric space. Many generalizations of a metric space have been appeared in the literature, for example, a quasi-metric space, a rectangular metric space, a *G*-metric space, an *S*-metric space, a *b*-metric space, and so on. Fixed point theory has been intensively studied and generalized using various approaches on these generalized metric spaces (see [4], [7], [8], [9], [10] and the references therein). In this paper, mainly, we consider the relationships among a metric, an *S*-metric and a *b*-metric.

The notion of an S-metric space has been introduced as follows:

Definition 1.1. [19] Let $X \neq \emptyset$. An S-metric on X is a function such that $\mathcal{S}: X \times X \times X \to [0, \infty)$ satisfying the following conditions for all $x, y, z, a \in X$: (S1) $\mathcal{S}(x, y, z) = 0$ if and only if x = y = z, (S2) $\mathcal{S}(x, y, z) \leq \mathcal{S}(x, x, a) + \mathcal{S}(y, y, a) + \mathcal{S}(z, z, a)$.

Then the pair (X, \mathcal{S}) is called an S-metric space.

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Recently, new fixed-point results have been proved using various approaches to find the existence and uniqueness conditions for a fixed point of a self-mapping on an S-metric space (see [4], [5], [6], [13], [14], [15], [19], [20] and [21]). By a geometric viewpoint, some geometric properties of the fixed point set of a self-mapping on an S-metric space have been studied in the non unique fixed point case (see [1], [3], [11], [12], [16], [17], [18], [22] and the references therein).

Some properties and relationships between a metric and an S-metric were studied by several authors (see [5], [6], [14], [19], [20] and [21] for more details). Topological equivalence is an important issue both for studies on fixed point theory and on topology (for example, see [23] and the references therein). Hence, we present the topological equivalence between a metric and an S-metric along with the relationships among a metric, an S-metric and a b-metric.

On the other hand, we focus on the fact that there exist some examples of an S-metric which does not always generate a metric (for example, see [14] for more details). We revisit the notion of a metric generated by an S-metric. Hence, the existing studies based on the metric generated by an S-metric can be updated using a general S-metric whether generate a metric or not.

At first, we recall the following definitions and lemmas which will be needed in the sequel.

Definition 1.2. [2] Let $X \neq \emptyset$. A *b*-metric on X is a function $d: X \times X \to [0, \infty)$ if there exists a real number $b \ge 1$ such that the following conditions are satisfied for all $x, y, z \in X$:

(B1) d(x, y) = 0 if and only if x = y, (B2) d(x, y) = d(y, x), (B3) $d(x, z) \le b [d(x, y) + d(y, z)]$. Then the pair (X, d) is called a *b*-metric space.

For more details on the recent fixed point results on b-metric spaces see the recent survey [9] and the references therein.

Definition 1.3. [19] Let (X, S) be an S-metric space.

- A sequence {x_n} in X converges to x if and only if S(x_n, x_n, x) → 0 as n → ∞. That is, there exists n₀ ∈ N such that for all n ≥ n₀, S(x_n, x_n, x) < ε for each ε > 0. We denote this by lim x_n = x or lim S(x_n, x_n, x) = 0.
 A sequence {x_n} in X is called a Cauchy sequence if S(x_n, x_n, x_m) → 0
- (2) A sequence $\{x_n\}$ in X is called a Cauchy sequence if $\mathcal{S}(x_n, x_n, x_m) \to 0$ as $n, m \to \infty$. That is, there exists $n_0 \in \mathbb{N}$ such that for all $n, m \ge n_0$, $\mathcal{S}(x_n, x_n, x_m) < \varepsilon$ for each $\varepsilon > 0$.
- (3) The S-metric space (X, S) is called complete if every Cauchy sequence is convergent.

Lemma 1.4. [19] Let (X, S) be an S-metric space. Then we have

$$\mathcal{S}(x, x, y) = \mathcal{S}(y, y, x).$$

Lemma 1.5. [19] Let (X, S) be an S-metric space. If $\lim_{n \to \infty} x_n = x$ and $\lim_{n \to \infty} y_n = y$ then $\lim_{n \to \infty} S(x_n, x_n, y_n) = S(x, x, y)$.

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2. Comparisons between metric and some generalized metrics

Let (X, \mathcal{S}) be an S-metric space. In [5], it was shown that every S-metric on X defines a metric d_S on X as follows:

$$d_S(x,y) = \mathcal{S}(x,x,y) + \mathcal{S}(y,y,x) = 2\mathcal{S}(x,x,y), \tag{1}$$

for all $x, y \in X$. However, in [14] it was noticed that the function d_S defined in (1) does not always define a metric because of the reason that the triangle inequality is not satisfied for all elements of X everywhen. Also, an example of an S-metric which does not generate a metric was given (see [14] for more details). We give another examples.

Example 2.1. Let $X = \{a, b, c\}$ and the function $S : X \times X \times X \to [0, \infty)$ be defined as

$$\begin{aligned} \mathcal{S}(a, a, c) &= \mathcal{S}(c, c, a) = 12, \\ \mathcal{S}(b, b, c) &= \mathcal{S}(c, c, b) = \mathcal{S}(a, a, b) = \mathcal{S}(b, b, a) = 5, \\ \mathcal{S}(x, y, z) &= 0 \text{ if } x = y = z, \\ \mathcal{S}(x, y, z) &= 1 \text{ if otherwise,} \end{aligned}$$

for all $x, y, z \in X$. Then the function S is an S-metric and the pair (X, S) is an S-metric space. However, the function d_S defined in (1) is not a metric on X. Indeed, for x = a, y = c and z = b, we get

$$d_S(a,c) = 24 \leq d_S(a,b) + d_S(b,c) = 20.$$

We note that the function d_S is called the metric generated by the S-metric S in the case that d_S is a metric.

Now, we give the relationship between an S-metric and a b-metric.

Proposition 2.2. Let (X, S) be an S-metric space and the function $d: X \times X \rightarrow [0, \infty)$ be defined as

$$d(x,y) = k\mathcal{S}(x,x,y),$$

for all $x, y \in X$ and some k > 0. Then the function d is a b-metric on X.

Proof. Using the condition (S1) and Lemma 1.4, we can easily seen that the conditions (B1) and (B2) are satisfied. Now we show that the condition (B3) is satisfied. From the condition (S2) and Lemma 1.4, we get

$$d(x,z) = kS(x,x,z) \le 2kS(x,x,y) + kS(z,z,y)$$

= $2kS(x,x,y) + kS(y,y,z)$
= $2d(x,y) + d(y,z)$ (2)

and

$$d(x,z) = k\mathcal{S}(x,x,z) = k\mathcal{S}(z,z,x) \le 2k\mathcal{S}(z,z,y) + k\mathcal{S}(x,x,y)$$

$$= 2k\mathcal{S}(y,y,z) + k\mathcal{S}(x,x,y)$$

$$= 2d(y,z) + d(x,y).$$
(3)

From the inequalities (2) and (3), we have

$$d(x,z) \le \frac{3}{2} \left[d(x,y) + d(y,z) \right]$$

Consequently, the function d is a b-metric with $b = \frac{3}{2}$.

Remark 2.3. 1) If we take k = 1 in Proposition 2.2 then we get Proposition 2.1 on page 116 in [20].

2) If we take k = 2 in Proposition 2.2 then we get the equality (1).

3) From Proposition 2.2, we deduce that the function d_S defined in (1) is a *b*-metric on X, but it is not always a metric since every *b*-metric need not to be a metric.

The relation between a metric and an S-metric is given in [6] as follows:

Lemma 2.4. [6] Let (X, d) be a metric space. Then the following properties are satisfied:

(1) $S_d(x, y, z) = d(x, z) + d(y, z)$ for all $x, y, z \in X$ is an S-metric on X.

(2) $x_n \to x$ in (X, d) if and only if $x_n \to x$ in (X, \mathcal{S}_d) .

(3) $\{x_n\}$ is Cauchy in (X, d) if and only if $\{x_n\}$ is Cauchy in (X, S_d) .

(4) (X, d) is complete if and only if (X, \mathcal{S}_d) is complete.

The metric S_d is called the *S*-metric generated by *d*.

Now we present the following properties with some illustrative examples.

Proposition 2.5. Let X be a nonempty set. If an S-metric is generated by any metric then this S-metric generates a metric d_S .

Proof. Let S_d be an S-metric on X generated by a metric d. Then by Lemma 2.4 we have

$$\mathcal{S}_d(x, y, z) = d(x, z) + d(y, z),$$

for all $x, y, z \in X$. Then we obtain

$$d_{\mathcal{S}_d}(x,y) = \mathcal{S}_d(x,x,y) + \mathcal{S}_d(y,y,x) = 2\mathcal{S}_d(x,x,y) = 2[d(x,y) + d(x,y)] = 4d(x,y),$$

for all $x, y \in X$. Since d is a metric on X, then the function $d_{\mathcal{S}_d}$ defines a metric on X.

We give the following corollary as a result of Proposition 2.5.

Corollary 2.6. Let X be a nonempty set. If an S-metric is generated by any metric d then we have

$$d_S(x,y) = 4d(x,y).$$

The converse of Proposition 2.5 is not always true as seen in the following example.

Example 2.7. Let $X = \mathbb{R}^2$ and define the function

$$S(x, y, z) = \sum_{i=1}^{2} \left(\left| x^{13} - z^{13} \right| + \left| x^{13} + z^{13} - 2y^{13} \right| \right),$$

for all $x = (x_1, x_2)$, $y = (y_1, y_2)$, $z = (z_1, z_2) \in \mathbb{R}^2$. Then the pair (\mathbb{R}^2, S) is an S-metric space with the S-metric which is not generated by any metric d, that is, $S \neq S_d$. On the contrary, we assume that there exists a metric d such that

$$\mathcal{S}(x, y, z) = \mathcal{S}_d(x, y, z) = d(x, z) + d(y, z)$$

for all $x, y, z \in \mathbb{R}^2$. Therefore we have

$$S(x, x, z) = 2d(x, z)$$
 and $d(x, z) = \sum_{i=1}^{2} |x^{13} - z^{13}|$

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and

$$S(y, y, z) = 2d(y, z)$$
 and $d(y, z) = \sum_{i=1}^{2} |y^{13} - z^{13}|$

for all $x, y, z \in \mathbb{R}^2$. So we get

$$\sum_{i=1}^{2} \left(\left| x^{13} - z^{13} \right| + \left| x^{13} + z^{13} - 2y^{13} \right| \right) = \sum_{i=1}^{2} \left(\left| x^{13} - z^{13} \right| + \left| y^{13} - z^{13} \right| \right),$$

which is a contradiction for x = (1, 1), y = (2, 2), $z = (0, 0) \in \mathbb{R}^2$. Consequently, $S \neq S_d$, that is, the S-metric is not generated by any metric d. However, this S-metric generates a metric d_S such that

$$d_{S}(x,y) = \mathcal{S}(x,x,y) + \mathcal{S}(y,y,x) = 2\mathcal{S}(x,x,y) = 2\sum_{i=1}^{2} |x^{13} - y^{13}|,$$

for all $x, y \in \mathbb{R}^2$.

Remark 2.8. Let X be a nonempty set, S_1 be an S-metric on X which is not generated by any metric d and S_2 be an S-metric on X which is generated by some metric d. Then d_{S_1} and d_{S_2} may be the same. For example, let $X = \mathbb{R}$ and the functions $S_1, S_2 : X \times X \times X \to [0, \infty)$ be defined as

$$S_1(x, y, z) = |x - z| + |x + z - 2y|$$

and

$$S_2(x, y, z) = |x - z| + |y - z|,$$

for all $x, y, z \in \mathbb{R}$. Then S_1 is an S-metric on \mathbb{R} which is not generated by any metric d and S_2 be an S-metric which is called usual S-metric on \mathbb{R} generated by usual metric d (see [14] and [20] for more details, respectively). By Lemma 2.4 we get

$$d_{S_1}(x,y) = d_{S_2}(x,y) = 4 |x-y|,$$

for all $x, y \in \mathbb{R}$. Consequently, S_1 and S_2 generate the same metric $d_S = d_{S_1} = d_{S_2}$.

Now we investigate another relationships between a metric and an S-metric with topological aspects. At first, we recall the following definitions and lemma on an S-metric space.

Definition 2.9. [19] Let (X, S) be an S-metric space. For r > 0 and $x \in X$, the open ball $B_S(x, r)$ with a center x and radius r is defined as follows:

$$B_S(x,r) = \{ y \in X : \mathcal{S}(x,x,y) < r \}.$$

Definition 2.10. [19] Let (X, S) be an S-metric space and $A \subseteq X$. For every $x \in A$, if there exists a r > 0 such that

$$B_S(x,r) \subseteq A,$$

then the subset A is called an open subset of X.

Lemma 2.11. [19] Let (X, S) be an S-metric space. If r > 0 and $x \in X$, the open ball $B_S(x, r)$ is an open subset of X.

In the following definition, we give the notion of topological equivalence of a metric and an S-metric.

Definition 2.12. Let (X, d) be a metric space and (X, S) be an S-metric space. The metric d and the S-metric S are said to be topological equivalent (briefly, equivalent) if they generate the same topology on X, that is, A is an open subset on (X, d) if and only if it is an open subset on (X, S).

Using this definition, we obtain the following proposition.

Proposition 2.13. Let (X, d) be a metric space and (X, S) be an S-metric space. Then the metric d and the S-metric S are equivalent if and only if there exist radii $r_1, r_2, \rho_1, \rho_2 > 0$ such that

$$B(x,r_1) \subset B_S(x,r_2)$$

and

$$B_S(x,\rho_1) \subset B(x,\rho_2)$$

for each $x \in X$.

Proof. Assume that the metric d and the S-metric S are equivalent. Let us consider an open ball $B_S(x, r_2)$ for each $x \in X$. Since the metric d and the S-metric S are equivalent then $B_S(x, r_2)$ is also open on (X, d). Therefore there exists an open ball such that

$$B(y,r_1) \subset B_S(x,r_2),$$

for each $y \in B_S(x, r_2)$. If we take x = y then we get

 $B(x, r_1) \subset B_S(x, r_2).$

Similarly we obtain

$$B_S(x,\rho_1) \subset B(x,\rho_2).$$

Conversely, let A be an open set on (X, d) and $x \in A$. Then there exists an open ball $B(x, \rho_2)$ such that

$$B(x,\rho_2) \subset A,$$

for each $x \in A$. By the hypothesis, there exists an open ball $B_S(x, \rho_1)$ on (X, S) such that

$$B_S(x,\rho_1) \subset B(x,\rho_2) \subset A$$

Then A is an open set on (X, S). Similarly, if A is an open set on (X, S) then A is an open set on (X, d).

Using the idea of projection to reduce three dimensions to two dimensions, we give the following definition.

Definition 2.14. Let (X, d) be a metric space and (X, S) be an S-metric space. If there exist numbers $k_1, k_2 > 0$ such that

$$k_1 \mathcal{S}(x, x, y) \le d(x, y) \le k_2 \mathcal{S}(x, x, y),$$

then the metric d and the S-metric S are said to (S, d)-Lipschitz equivalent.

In the following proposition we see the relationships between topological equivalence and (S, d)-Lipschitz equivalence.

Proposition 2.15. Let (X, d) be a metric space and (X, S) be an S-metric space. If the metric d and the S-metric S are (S, d)-Lipschitz equivalent then they are equivalent. EJMAA-2023/11(2)

Proof. We prove that the metric d and the S-metric S are equivalent. To do this, we show that $B(x, k_1 r) \subset B_S(x, r)$ and $B_S\left(x, \frac{r}{k_2}\right) \subset B(x, r)$. Assume that $y \in B(x, k_1 r)$. Then we get

$$d(x,y) \le k_1 r$$
 and $\frac{d(x,y)}{k_1} \le r$.

Hence we obtain

$$S(x,x,y) \leq \frac{d(x,y)}{k_1} \leq r$$

that is, $y \in B_S(x, r)$. Therefore we have

$$B(x,k_1r) \subset B_S(x,r).$$

Using the above arguments, we see that

$$B_S\left(x,\frac{r}{k_2}\right) \subset B(x,r).$$

Consequently, the metric d and the S-metric S are equivalent.

Proposition 2.16. Let (X, d) be a metric space and (X, S_d) be an S-metric space with the S-metric S_d generated by d. Then the metric d and the S-metric S_d are equivalent.

Proof. Since S_d is an S-metric generated by d, then from Lemma 2.4 we get

$$\mathcal{S}_d(x, y, z) = d(x, z) + d(y, z)$$

and so

$$\mathcal{S}_d(x, x, y) = 2d(x, y).$$

Therefore we have

$$\frac{1}{2}\mathcal{S}_d(x,x,y) \le d(x,y) \le \mathcal{S}_d(x,x,y),$$

for $k_1 = \frac{1}{2}$, $k_2 = 1$. Consequently, from Proposition 2.15 the metric d and the *S*-metric S_d are equivalent.

Remark 2.17. Notice that a metric and an S-metric which is not generated by any metric can be equivalent. For example, let us consider the S-metric S_1 defined in Remark 2.8 and the usual metric on \mathbb{R} . Therefore the usual metric and the S-metric S_1 are equivalent.

Finally, even if an S-metric space is topologically equivalent to a metric space, but they are isometrically distinct.

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